

CALCULUS

Lecture 12: Laplace Transforms

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WHY LAPLACE TRANSFORMS?

Solving differential equations directly can be tedious. Laplace transforms offer a systematic algebraic approach.

Key advantages:

- Converts a DE into an **algebraic equation** — easy to manipulate
- Initial conditions are **built in** from the start (no separate step)
- Handles **discontinuous** or piecewise forcing functions naturally

The transform pathway:

$$\underbrace{y'' + 3y' + 2y = e^{4t}}_{\text{ODE (hard)}} \xrightarrow{\mathcal{L}} \underbrace{\text{Algebraic equation in } Y(s)}_{\text{Easy to solve}} \xrightarrow{\mathcal{L}^{-1}} y(t)$$

DEFINITION OF THE LAPLACE TRANSFORM

Definition

The **Laplace transform** of a function $f(t)$ is:

$$\mathcal{L}\{f(t)\} = \int_0^{\infty} f(t) e^{-st} dt = F(s)$$

provided the integral converges, which requires s to be sufficiently large.

- t : time variable (or independent variable); $f(t)$: function in **time domain**
- s : complex frequency parameter; $F(s)$: function in **s-domain**
- $f(t)$ and $F(s)$ form a **transform pair**: $f(t) \longleftrightarrow F(s)$

Example: $\mathcal{L}\{e^{at}\} = F(s)$ exists for $s > a$ (we will derive this shortly).

LINEARITY OF THE LAPLACE TRANSFORM

Linearity

For constants a, b and functions $f(t), g(t)$:

$$\mathcal{L}\{af(t) + bg(t)\} = aF(s) + bG(s)$$

Proof: Follows directly from linearity of integration:

$$\int_0^{\infty} [af + bg]e^{-st} dt = a \int_0^{\infty} f e^{-st} dt + b \int_0^{\infty} g e^{-st} dt$$

Examples (using the table we will build):

$$\mathcal{L}\{3e^{2t} - 5\sin(4t)\} = \frac{3}{s-2} - \frac{20}{s^2+16}$$

$$\mathcal{L}\{2t^3 + 7\cos(3t)\} = \frac{12}{s^4} + \frac{7s}{s^2+9}$$

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$\mathcal{L}\{1\}$ FROM THE DEFINITION

Evaluate directly using the definition:

$$\begin{aligned}\mathcal{L}\{1\} &= \int_0^{\infty} 1 \cdot e^{-st} dt = \left[\frac{e^{-st}}{-s} \right]_0^{\infty} \\ &= \lim_{t \rightarrow \infty} \frac{e^{-st}}{-s} - \frac{e^0}{-s} = 0 + \frac{1}{s}\end{aligned}$$

$$\mathcal{L}\{1\} = \frac{1}{s}, \quad s > 0$$

(The limit $\lim_{t \rightarrow \infty} e^{-st} = 0$ holds because $s > 0$.)

$\mathcal{L}\{t\}$ AND $\mathcal{L}\{t^n\}$

Deriving $\mathcal{L}\{t\}$ by Integration by Parts: Let $u = t$, $dv = e^{-st} dt$:

$$\mathcal{L}\{t\} = \left[\frac{-t e^{-st}}{s} \right]_0^{\infty} + \frac{1}{s} \int_0^{\infty} e^{-st} dt = 0 + \frac{1}{s} \cdot \frac{1}{s} = \frac{1}{s^2}$$

General pattern (by repeated IBP or the Gamma function):

$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}}, \quad n = 0, 1, 2, \dots, \quad s > 0$$

Examples:

$$\mathcal{L}\{t^2\} = \frac{2}{s^3} \quad \mathcal{L}\{t^3\} = \frac{6}{s^4} \quad \mathcal{L}\{t^5\} = \frac{120}{s^6}$$

$$\mathcal{L}\{e^{at}\}$$

$$\begin{aligned}\mathcal{L}\{e^{at}\} &= \int_0^{\infty} e^{at} \cdot e^{-st} dt = \int_0^{\infty} e^{-(s-a)t} dt \\ &= \left[\frac{e^{-(s-a)t}}{-(s-a)} \right]_0^{\infty} = 0 + \frac{1}{s-a}\end{aligned}$$

$$\mathcal{L}\{e^{at}\} = \frac{1}{s-a}, \quad s > a$$

Examples:

$$\mathcal{L}\{e^{3t}\} = \frac{1}{s-3} \quad (s > 3)$$

$$\mathcal{L}\{e^{-5t}\} = \frac{1}{s+5} \quad (s > -5)$$

$$\mathcal{L}\{\sin(kt)\}$$

Let $I = \mathcal{L}\{\sin(kt)\}$. Apply integration by parts twice (first: $u = \sin(kt)$, $dv = e^{-st} dt$):

$$I = \underbrace{\left[\frac{-e^{-st} \sin(kt)}{s} \right]_0^\infty}_{=0} + \frac{k}{s} \mathcal{L}\{\cos(kt)\}$$

Now apply integration by parts to $\mathcal{L}\{\cos(kt)\}$ ($u = \cos(kt)$, $dv = e^{-st} dt$):

$$\mathcal{L}\{\cos(kt)\} = \frac{1}{s} - \frac{k}{s} I$$

Substituting back:

$$I = \frac{k}{s} \left(\frac{1}{s} - \frac{k}{s} I \right) = \frac{k}{s^2} - \frac{k^2}{s^2} I \implies I \left(1 + \frac{k^2}{s^2} \right) = \frac{k}{s^2}$$

$$\mathcal{L}\{\sin(kt)\} = \frac{k}{s^2 + k^2}$$

$$\mathcal{L}\{\cos(kt)\}$$

Use the derivative relation $\frac{d}{dt}[\sin(kt)] = k \cos(kt)$ and the derivative rule $\mathcal{L}\{f'(t)\} = s\mathcal{L}\{f(t)\} - f(0)$ (derived on the next slide):

$$\mathcal{L}\left\{\frac{d}{dt}[\sin(kt)]\right\} = s \cdot \mathcal{L}\{\sin(kt)\} - \sin(0)$$

$$k \mathcal{L}\{\cos(kt)\} = s \cdot \frac{k}{s^2 + k^2} - 0$$

Dividing both sides by k :

$$\mathcal{L}\{\cos(kt)\} = \frac{s}{s^2 + k^2}$$

Examples:

$$\mathcal{L}\{\sin(3t)\} = \frac{3}{s^2 + 9} \quad \mathcal{L}\{\cos(5t)\} = \frac{s}{s^2 + 25}$$

STANDARD TRANSFORM TABLE

$f(t)$	$F(s) = \mathcal{L}\{f(t)\}$
1	$\frac{1}{s}, \quad s > 0$
t^n	$\frac{n!}{s^{n+1}}, \quad s > 0$
e^{at}	$\frac{1}{s-a}, \quad s > a$
$\sin(kt)$	$\frac{k}{s^2 + k^2}$
$\cos(kt)$	$\frac{s}{s^2 + k^2}$
$e^{at} \sin(kt)$	$\frac{k}{(s-a)^2 + k^2}$
$e^{at} \cos(kt)$	$\frac{s-a}{(s-a)^2 + k^2}$

USING THE TABLE: EXAMPLES

Apply the table with linearity to find transforms directly.

Example 1: Find $\mathcal{L}\{4t^2 - 3e^{-2t} + 5\sin(3t)\}$

$$= 4 \cdot \frac{2!}{s^3} - 3 \cdot \frac{1}{s+2} + 5 \cdot \frac{3}{s^2+9} = \frac{8}{s^3} - \frac{3}{s+2} + \frac{15}{s^2+9}$$

Example 2: Find $\mathcal{L}\{e^{-t}\cos(2t) + 3e^{5t}\}$

$$= \frac{s+1}{(s+1)^2+4} + \frac{3}{s-5}$$

Example 3: Find $\mathcal{L}\{6 - 2t^3 + 4\cos(t)\}$

$$= \frac{6}{s} - \frac{12}{s^4} + \frac{4s}{s^2+1}$$

DERIVATIVE RULE: $\mathcal{L}\{f'\}$ AND $\mathcal{L}\{f''\}$

Derivation (integration by parts with $u = e^{-st}$, $dv = f'(t)dt$):

$$\begin{aligned}\mathcal{L}\{f'(t)\} &= \left[e^{-st}f(t) \right]_0^{\infty} + s \int_0^{\infty} f(t)e^{-st} dt \\ &= (0 - f(0)) + sF(s)\end{aligned}$$

$$\mathcal{L}\{f'(t)\} = sF(s) - f(0)$$

Applying the rule again to $f'' = (f')'$:

$$\mathcal{L}\{f''(t)\} = s \mathcal{L}\{f'(t)\} - f'(0) = s[sF(s) - f(0)] - f'(0)$$

$$\mathcal{L}\{f''(t)\} = s^2F(s) - sf(0) - f'(0)$$

DERIVATIVE RULE: VERIFICATION

Check 1: Let $f(t) = e^{at}$, so $f'(t) = ae^{at}$ and $f(0) = 1$.

$$\text{LHS: } \mathcal{L}\{ae^{at}\} = \frac{a}{s-a}$$

$$\text{RHS: } sF(s) - f(0) = \frac{s}{s-a} - 1 = \frac{s - (s-a)}{s-a} = \frac{a}{s-a} \quad \checkmark$$

Check 2: Let $g(t) = \sin(kt)$, so $g'(t) = k \cos(kt)$ and $g(0) = 0$.

$$\text{LHS: } \mathcal{L}\{k \cos(kt)\} = \frac{ks}{s^2 + k^2}$$

$$\text{RHS: } s \cdot \frac{k}{s^2 + k^2} - 0 = \frac{ks}{s^2 + k^2} \quad \checkmark$$

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INVERSE LT — DEFINITION AND TABLE LOOKUP

Definition

Given $F(s)$, the **inverse Laplace transform** $\mathcal{L}^{-1}\{F(s)\} = f(t)$ is the unique function whose transform is $F(s)$.

Linearity: $\mathcal{L}^{-1}\{aF + bG\} = a\mathcal{L}^{-1}\{F\} + b\mathcal{L}^{-1}\{G\}$

Direct table lookup:

$$\mathcal{L}^{-1}\left\{\frac{3}{s^2}\right\} = 3t \quad (\text{since } \mathcal{L}\{t\} = 1/s^2)$$

$$\mathcal{L}^{-1}\left\{\frac{5}{s+4}\right\} = 5e^{-4t}$$

$$\mathcal{L}^{-1}\left\{\frac{6}{s^2+9}\right\} = 2\sin(3t) \quad (\text{factor: } 6 = 2 \cdot 3, k = 3)$$

COMPLETING THE SQUARE

When the denominator is a quadratic with no real roots, complete the square to match table entries.

Example 1: Find $\mathcal{L}^{-1}\left\{\frac{2}{s^2 + 4s + 8}\right\}$

$$s^2 + 4s + 8 = (s + 2)^2 + 4$$

$$\frac{2}{(s + 2)^2 + 4} = \frac{2}{(s + 2)^2 + 2^2} \longrightarrow e^{-2t} \sin(2t)$$

Example 2: Find $\mathcal{L}^{-1}\left\{\frac{s + 1}{s^2 + 2s + 10}\right\}$

$$s^2 + 2s + 10 = (s + 1)^2 + 9$$

$$\frac{s + 1}{(s + 1)^2 + 9} \longrightarrow e^{-t} \cos(3t)$$

PARTIAL FRACTIONS: TYPE 1 — DISTINCT REAL ROOTS

For $F(s) = \frac{N(s)}{(s-a)(s-b)}$, write $\frac{N(s)}{(s-a)(s-b)} = \frac{A}{s-a} + \frac{B}{s-b}$.

Cover-up: multiply by $(s-a)$ and set $s = a$ to find A ; similarly for B .

Example: Find $\mathcal{L}^{-1}\left\{\frac{6}{s(s+3)}\right\}$

$$\frac{6}{s(s+3)} = \frac{A}{s} + \frac{B}{s+3}$$

$$A = \left.\frac{6}{s+3}\right|_{s=0} = 2, \quad B = \left.\frac{6}{s}\right|_{s=-3} = -2$$

$$\mathcal{L}^{-1}\left\{\frac{2}{s} - \frac{2}{s+3}\right\} = 2 - 2e^{-3t}$$

PARTIAL FRACTIONS: TYPE 2 — QUADRATIC DENOMINATOR

For an irreducible quadratic factor, use $\frac{Bs + C}{s^2 + ps + q}$ in the decomposition.

Example: Find $\mathcal{L}^{-1}\left\{\frac{s+3}{(s-2)(s^2+1)}\right\}$

$$\frac{s+3}{(s-2)(s^2+1)} = \frac{A}{s-2} + \frac{Bs+C}{s^2+1}$$

Multiply through: $s+3 = A(s^2+1) + (Bs+C)(s-2)$

$$s = 2 : 5 = 5A \Rightarrow A = 1$$

$$s = 0 : 3 = A - 2C = 1 - 2C \Rightarrow C = -1$$

$$s^2 \text{ coeff : } 0 = A + B \Rightarrow B = -1$$

$$\frac{1}{s-2} - \frac{s+1}{s^2+1} = \frac{1}{s-2} - \frac{s}{s^2+1} - \frac{1}{s^2+1} \longrightarrow e^{2t} - \cos t - \sin t$$

PRACTICE: INVERSE LAPLACE TRANSFORM

Problem 1: Find $\mathcal{L}^{-1}\left\{\frac{6}{(s+1)(s+4)}\right\}$

Solution:
$$\frac{6}{(s+1)(s+4)} = \frac{A}{s+1} + \frac{B}{s+4}$$

$$A = \frac{6}{s+4}\bigg|_{s=-1} = 2, \quad B = \frac{6}{s+1}\bigg|_{s=-4} = -2$$

$$f(t) = 2e^{-t} - 2e^{-4t}$$

Problem 2: Find $\mathcal{L}^{-1}\left\{\frac{3}{s^2 + 2s + 5}\right\}$

Solution: $s^2 + 2s + 5 = (s+1)^2 + 4$, so $\frac{3}{(s+1)^2 + 4} =$

$$\frac{3}{2} \cdot \frac{2}{(s+1)^2 + 4}$$

$$f(t) = \frac{3}{2} e^{-t} \sin(2t)$$

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THE 4-STEP ALGORITHM

Algorithm for solving IVPs via Laplace Transforms

- 1 **Transform** both sides of the ODE using $\mathcal{L}$; apply derivative rules $\mathcal{L}\{y'\} = sY - y(0)$, $\mathcal{L}\{y''\} = s^2Y - sy(0) - y'(0)$
- 2 **Solve** the resulting algebraic equation for $Y(s)$
- 3 **Decompose** $Y(s)$ using partial fractions if needed
- 4 **Invert** to find $y(t) = \mathcal{L}^{-1}\{Y(s)\}$ using the table

The key insight: ICs are automatically encoded in Step 1 — no separate particular vs. homogeneous split needed.

EXAMPLE 1: $y' + 3y = 0, \quad y(0) = 2$

Step 1: Transform.

$$\mathcal{L}\{y'\} + 3\mathcal{L}\{y\} = 0 \implies [sY(s) - y(0)] + 3Y(s) = 0$$

Step 2: Substitute IC and solve for $Y(s)$.

$$sY - 2 + 3Y = 0$$

$$(s + 3)Y = 2 \implies Y(s) = \frac{2}{s + 3}$$

Step 4: Invert.

$$y(t) = \mathcal{L}^{-1}\left\{\frac{2}{s + 3}\right\} = 2e^{-3t}$$

Quick check: $y' + 3y = -6e^{-3t} + 6e^{-3t} = 0 \checkmark$ and $y(0) = 2$
 $\checkmark$

EXAMPLE 2: $y' + 3y = 6$, $y(0) = 0$ — SETUP

Step 1: Transform.

$$[sY - 0] + 3Y = \mathcal{L}\{6\} = \frac{6}{s}$$

Step 2: Solve for $Y(s)$.

$$(s + 3)Y = \frac{6}{s} \implies Y(s) = \frac{6}{s(s + 3)}$$

Step 3: Partial fractions.

$$\frac{6}{s(s + 3)} = \frac{A}{s} + \frac{B}{s + 3}$$

$$A = \frac{6}{s + 3} \Big|_{s=0} = 2 \qquad B = \frac{6}{s} \Big|_{s=-3} = -2$$

$$Y(s) = \frac{2}{s} - \frac{2}{s + 3}$$

EXAMPLE 2: INVERSE TRANSFORM AND SOLUTION

Step 4: Invert.

$$y(t) = \mathcal{L}^{-1}\left\{\frac{2}{s}\right\} - \mathcal{L}^{-1}\left\{\frac{2}{s+3}\right\} = 2 - 2e^{-3t}$$

Verification:

$$y'(t) = 6e^{-3t}$$

$$y' + 3y = 6e^{-3t} + 3(2 - 2e^{-3t}) = 6e^{-3t} + 6 - 6e^{-3t} = 6 \quad \checkmark$$

$$y(0) = 2 - 2 = 0 \quad \checkmark$$

Note: As $t \rightarrow \infty$, $y \rightarrow 2$ — the steady state equals the constant forcing divided by the coefficient: $6/3 = 2$.

EXAMPLE 3: $y' + 3y = 13 \sin(2t)$, $y(0) = 6$ — SETUP

$$\text{Step 1: } [sY - 6] + 3Y = \frac{26}{s^2 + 4} \quad \text{Step 2: } (s+3)Y = \frac{26}{s^2 + 4} + 6$$

$$\implies Y(s) = \frac{26}{(s+3)(s^2+4)} + \frac{6}{s+3}$$

Step 3: Partial fractions for the first term.

$$\frac{26}{(s+3)(s^2+4)} = \frac{A}{s+3} + \frac{Bs+C}{s^2+4}$$

Multiply through: $26 = A(s^2 + 4) + (Bs + C)(s + 3)$

$$s = -3 : 26 = 13A \implies A = 2$$

$$s = 0 : 26 = 4A + 3C = 8 + 3C \implies C = 6$$

$$s^2 : 0 = A + B \implies B = -2$$

EXAMPLE 3: FINAL SOLUTION

Combining the partial fractions:

$$\frac{26}{(s+3)(s^2+4)} = \frac{2}{s+3} + \frac{-2s+6}{s^2+4} = \frac{2}{s+3} - \frac{2s}{s^2+4} + \frac{6}{s^2+4}$$

Adding back $\frac{6}{s+3}$:

$$Y(s) = \frac{8}{s+3} - \frac{2s}{s^2+4} + \frac{3 \cdot 2}{s^2+4}$$

Step 4: Invert.

$$y(t) = 8e^{-3t} - 2\cos(2t) + 3\sin(2t)$$

Check at $t = 0$: $y(0) = 8 - 2 + 0 = 6 \checkmark$

SECOND-ORDER DERIVATIVE RULE

For a second-order ODE, we need $\mathcal{L}\{y''\}$.

Second-Order Transform Rule

$$\mathcal{L}\{y''(t)\} = s^2 Y(s) - s y(0) - y'(0)$$

Derivation: Apply $\mathcal{L}\{f'\} = sF - f(0)$ twice, treating $y'' = (y')'$:

$$\mathcal{L}\{y''\} = s \mathcal{L}\{y'\} - y'(0) = s[sY - y(0)] - y'(0)$$

Both initial conditions $y(0)$ and $y'(0)$ appear automatically.

The ODE $ay'' + by' + cy = g(t)$ transforms to:

$$a[s^2 Y - sy(0) - y'(0)] + b[sY - y(0)] + cY = G(s)$$

EXAMPLE 4: $y'' + 3y' + 2y = e^{4t}$,
 $y(0) = y'(0) = 0$ — SETUP

Step 1: Transform.

$$\begin{aligned}[s^2 Y - 0 - 0] + 3[sY - 0] + 2Y &= \frac{1}{s - 4} \\ (s^2 + 3s + 2)Y &= \frac{1}{s - 4}\end{aligned}$$

Step 2: Solve for $Y(s)$.

$$Y(s) = \frac{1}{(s^2 + 3s + 2)(s - 4)} = \frac{1}{(s + 1)(s + 2)(s - 4)}$$

Step 3: Set up partial fractions.

$$\frac{1}{(s + 1)(s + 2)(s - 4)} = \frac{A}{s + 1} + \frac{B}{s + 2} + \frac{C}{s - 4}$$

EXAMPLE 4: PARTIAL FRACTIONS

Multiply through: $1 = A(s+2)(s-4) + B(s+1)(s-4) + C(s+1)(s+2)$

Cover-up at each root:

$$s = -1 : 1 = A(1)(-5) = -5A \implies A = -\frac{1}{5}$$

$$s = -2 : 1 = B(-1)(-6) = 6B \implies B = \frac{1}{6}$$

$$s = 4 : 1 = C(5)(6) = 30C \implies C = \frac{1}{30}$$

$$Y(s) = \frac{-1/5}{s+1} + \frac{1/6}{s+2} + \frac{1/30}{s-4}$$

EXAMPLE 4: FINAL SOLUTION

Step 4: Invert.

$$y(t) = -\frac{1}{5}e^{-t} + \frac{1}{6}e^{-2t} + \frac{1}{30}e^{4t}$$

Verification at $t = 0$:

$$y(0) = -\frac{1}{5} + \frac{1}{6} + \frac{1}{30} = \frac{-6 + 5 + 1}{30} = 0 \quad \checkmark$$

$$y'(t) = \frac{1}{5}e^{-t} - \frac{1}{3}e^{-2t} + \frac{2}{15}e^{4t}$$

$$y'(0) = \frac{1}{5} - \frac{1}{3} + \frac{2}{15} = \frac{3 - 5 + 2}{15} = 0 \quad \checkmark$$

PRACTICE PROBLEMS

Problem 1: Solve $y' + 2y = 4$, $y(0) = 1$.

Solution: $(s + 2)Y - 1 = 4/s \implies Y = (s + 4)/(s(s + 2))$

PF: $A = 4/(s + 2)|_{s=0} = 2$, $B = (s + 4)/s|_{s=-2} = -1$

$$y(t) = 2 - e^{-2t} \quad [\text{Check: } y(0) = 1 \checkmark]$$

Problem 2: Solve $y'' - y = \cos t$, $y(0) = 0$, $y'(0) = 0$.

Solution: $(s^2 - 1)Y = s/(s^2 + 1) \implies Y = s/((s - 1)(s + 1)(s^2 + 1))$

PF: $A = 1/4$, $B = 1/4$, $C = -1/2$, $D = 0$

$$y(t) = \frac{1}{4}e^t + \frac{1}{4}e^{-t} - \frac{1}{2}\cos t \quad [\text{Check: } y(0) = 0 \checkmark]$$

Thank You